## Optimization of Some Non-Convex Functionals Arising in Information Theory



Dept. of Information Engg., The Chinese University of Hong Kong
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## Introduction

A non-convex functional family of interest
Given a vector of discrete random variables $X^{n}:=\left(X_{1}, \cdots, X_{n}\right)$ taking values in $\otimes_{i=1}^{n} \mathcal{X}_{i}$ and $d_{X^{n}}: \otimes_{i=1}^{n} \mathcal{X}_{i} \rightarrow \mathbb{R}$ some arbitrary vector:

$$
G\left(d_{X^{n}}\right):=\max _{p_{X^{n}}}\left(\sum_{S \subset[1: n]} \alpha_{S} H\left(X_{S}\right)-E_{p_{X^{n}}}\left(d_{X^{n}}\right)\right)
$$

where $S$ is a subset of $[1: n], X_{S}$ denotes the set $\left\{X_{i}: i \in S\right\}$, and $\alpha_{S} \in \mathbb{R}$ depends on $S$.

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Why is this functional family interesting?

- The evaluation of certain achievable rate regions or bounds to the capacity region canonically involves functionals of the above form.
- If the global optimizers of a natural "product"-extension of a functional (corresponding to an achievable rate region) are product distributions, then the achievable rate regions can be shown to be optimal in many settings.


## Lossless source coding with one helper



Figure 1: Lossless source coding with one helper
What is the optimal rate region $\mathscr{R}\left(p_{X Y}\right)$ ?

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What is the optimal rate region $\mathscr{R}\left(p_{X Y}\right)$ ?

Theorem 1.1, [Ahlswede-Körner 1975; Wyner 1975]
Let $(X, Y) \sim p_{X Y}$ be a discrete memoryless source. The optimal rate region $\mathscr{R}\left(p_{X Y}\right)$ for loseless source coding of $Y$ with a helper observing $X$ is the set of rate pairs ( $R_{1}, R_{2}$ ) such that

$$
\begin{aligned}
& R_{1} \geq H(Y \mid U) \\
& R_{2} \geq I(U ; X)
\end{aligned}
$$

for some conditional pmf $p_{U \mid X}$, where $|\mathcal{U}| \leq|\mathcal{X}|+1$.

Lossless source coding with one helper


Figure 1: Lossless source coding with one helper
What is the optimal rate region $\mathscr{R}\left(p_{X Y}\right)$ ?
The optimal rate region is always convex by time-sharing argument.

Evaluation of the region: using weighted sum rates (supporting hyperplanes)

$$
\begin{aligned}
\min _{\left(R_{1}, R_{2}\right) \text { achievable }} R_{1}+\gamma R_{2} & =\min _{p_{U \mid X}} H(Y \mid U)+\gamma I(U ; X) \\
& =\gamma H(X)+\min _{p_{U \mid X}}[H(Y \mid U)-\gamma H(X \mid U)] \\
& =\gamma H(X)-\mathfrak{C}_{q_{X}}[\gamma H(X)-H(Y)]\left(p_{X}\right)
\end{aligned}
$$

Non-trivial regime: $\gamma \in(0,1)$. It becomes a non-convex optimization problem.

## Upper Concave Envelope and Duality (Fenchel)

Define $f\left(q_{X}\right):=\gamma H(X)-H(Y)$.
Upper Concave Envelope and Lower Convex Envelope (Example on next slide)

$$
\begin{aligned}
& \mathfrak{C}_{q_{X}}[f]:=\inf \left\{g: g \text { is concave w.r.t. } q_{X} \text { and } g\left(q_{X}\right) \geq f\left(q_{X}\right), \forall q_{X}\right\} \\
& \mathfrak{K}_{q_{X}}[f]:=-\mathfrak{C}_{q_{X}}[-f]
\end{aligned}
$$

Fenchel's Dual Representation
Given $d_{X}=\left(d_{x}, x \in \mathcal{X}\right)$ a real-valued vector of length $|\mathcal{X}|$, the Fenchel-dual of the function, $f\left(q_{X}\right)$, is

$$
f^{\dagger}\left(d_{X}\right):=\sup _{q_{X}}\left\{\gamma H(X)-H(Y)-E_{q_{X}}\left(d_{X}\right)\right\}
$$

The dual variables $d_{x}$ define hyperplanes, and $f^{\dagger}\left(d_{X}\right)$ is convex in $d_{X}$.

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\begin{aligned}
f^{\dagger}\left(d_{X}\right) & :=\sup _{q_{X}}\left\{\gamma H(X)-H(Y)-E_{q_{X}}\left(d_{X}\right)\right\} . \\
\mathfrak{C}_{q_{X}}[f]\left(p_{X}\right) & =\inf _{d_{X}}\left\{f^{\dagger}\left(d_{X}\right)+\sum_{x \in \mathcal{X}} d_{x} p_{X}(x)\right\}
\end{aligned}
$$

- The dual of the dual yields the upper concave envelope.
- Computing the dual of $f^{\dagger}\left(d_{X}\right)$ is a convex-optimization problem. Therefore, the main difficulty lies in computing the dual function, $f^{\dagger}\left(d_{X}\right)$.


## Plot of Upper Concave Envelope

Simple Observation: Suffices to determine the extremal distributions, that is, the set of $p_{X}$ satisfying $\mathfrak{C}_{q_{X}}[f]\left(p_{X}\right)=f\left(p_{X}\right)$.
Example: Consider $\mathrm{P}(X=0)=x, \mathrm{P}(X=1)=1-x$.
$f(x)=0.3 H(X)-H(Y)=0.3 H_{2}(x)-H_{2}(0.8 x+0.2(1-x))$.


## Outline

(1) Hypercontractive Region Evaluation

- Introduction to Hypercontractivity
- Main Results on Hypercontractivity
(2) Lower Bounds on Distributed Source Coding
- Körner and Marton's Modulo Two Sum Problem
- Alternative Proofs to Quadratic Gaussian CEO Problem and Distributed Source Coding Problem
(3) Log-Convexity of Fisher Information
- Motivations
- Proof to log-convexity of Fisher information


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## Definitions of Hypercontractivity

Hypercontractive Region Evaluation
Norm

$$
\left.\|Z\|_{\lambda}:=E\left(|Z|^{\lambda}\right)^{\frac{1}{\lambda}}, \lambda \neq 0, \quad \text { (normalized } \lambda \text { moment }\right) ; \quad\|Z\|_{0}:=e^{E(\log |Z|)}
$$

Forward hypercontractivity
A pair of random variables $(X, Y)$ is said to be $\left(\lambda_{1}, \lambda_{2}\right)$ forward hypercontractive, for $\lambda_{1}, \lambda_{2} \in(1, \infty)$, if

$$
E(f(X) g(Y)) \leq\|f(X)\|_{\lambda_{1}}\|g(Y)\|_{\lambda_{2}}
$$

holds for all non-negative functions $f(\cdot), g(\cdot)$.

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$$

holds for all non-negative functions $f(\cdot), g(\cdot)$.
Reverse hypercontractivity
A pair of random variables $(X, Y)$ is said to be $\left(\lambda_{1}, \lambda_{2}\right)$ reverse hypercontractive, for $\lambda_{1}, \lambda_{2} \in(-\infty, 1)$, if

$$
E(f(X) g(Y)) \geq\|f(X)\|_{\lambda_{1}}\|g(Y)\|_{\lambda_{2}}
$$

holds for all positive functions $f(\cdot), g(\cdot)$.

Known hypercontractivity parameters

Binary Symmetric Channel (BSC) with uniform input: [Bonami 1970; Borell 1982] Consider a uniformly distributed binary valued $X$ and $Y$ obtained by passing $X$ through a BSC with crossover probability $\frac{1-\rho}{2} .(X, Y)$ is $\left(\lambda_{1}, \lambda_{2}\right)$ forward (reverse) hypercontractive if and only if

$$
\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq \rho^{2}
$$

Gaussian: [Gross 1975, Borell 1982]
Let $(X, Y) \sim N\left(0,\left[\begin{array}{ll}1 & \rho \\ \rho & 1\end{array}\right]\right),(X, Y)$ is $\left(\lambda_{1}, \lambda_{2}\right)$ forward (reverse) hypercontractive if and only if

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These hypercontractive parameters have found applications in theoretical computer science, see [Kahn-Kalai-Linial 1988; Mossel-O’Donnell-Rubinfeld-Servedio 2006].

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A natural question (thanks: V. Guruswami and J. Radhakrishnan): What is the hypercontractive region for binary erasure channel with uniform inputs?

## Equivalent characterizations of forward hypercontractivity

Hypercontractive Region Evaluation
Equivalent characterizations of hypercontractivity [Nair 2014]
Let $(X, Y) \sim p_{X Y}$. The following assertions are equivalent:
(1) For all non-negative functions $f(\cdot), g(\cdot)$,

$$
E(f(X) g(Y)) \leq\|f(X)\|_{\lambda_{1}}\|g(Y)\|_{\lambda_{2}}
$$

(2) For every $q_{X Y}\left(\ll p_{X Y}\right)$ we have (also appeared in [Carlen-Cordero-Erausquin 2009])

$$
\frac{1}{\lambda_{1}} D\left(q_{X} \| p_{X}\right)+\frac{1}{\lambda_{2}} D\left(q_{Y} \| p_{Y}\right) \leq D\left(q_{X Y} \| p_{X Y}\right)
$$

(3) For every extension $p_{U \mid X Y}$ such that $I(U ; X Y)>0$ we have

$$
\frac{1}{\lambda_{1}} I(U ; X)+\frac{1}{\lambda_{2}} I(U ; Y) \leq I(U ; X Y)
$$

(1) Let $\mathfrak{K}[f]_{x}$ represents the lower convex envelope of the function $f$ evaluated at $x$.

$$
\mathfrak{K}\left[\frac{1}{\lambda_{1}} H(X)+\frac{1}{\lambda_{2}} H(Y)-H(X Y)\right]_{p_{X Y}}=\frac{1}{\lambda_{1}} H(X)+\frac{1}{\lambda_{2}} H(Y)-H(X Y)
$$

Equivalent characterizations of reverse hypercontractivity
[Beigi-Nair 2016]
Hypercontractive Region Evaluation
Denote the reverse hypercontractive region of $\left(\lambda_{1}, \lambda_{2}\right)$ for a pair of random variables $(X, Y)$ distributed according to $p_{X Y}$ as $R^{r}(X, Y)$.

Equivalent characterizations of reverse hypercontractivity
(1) The pair $\left(\lambda_{1}, \lambda_{2}\right)$ with $0<\lambda_{1}<1,0<\lambda_{2}<1$ belongs to $R^{r}(X, Y)$ if and only if for any $q_{X}$ and $q_{Y}$ there exists $r_{X Y}$ with $r_{X}=q_{X}$ and $r_{Y}=q_{Y}$ such that:

$$
\frac{1}{\lambda_{1}} D\left(q_{X} \| p_{X}\right)+\frac{1}{\lambda_{2}} D\left(q_{Y} \| p_{Y}\right) \geq D\left(r_{X Y} \| p_{X Y}\right)
$$

(2) The pair $\left(\lambda_{1}, \lambda_{2}\right)$ with $0<\lambda_{1}<1, \lambda_{2}<0$ belongs to $R^{r}(X, Y)$ if and only if for any $q_{X}$ there exists $r_{X Y}$ with $r_{X}=q_{X}$ such that:

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(3) The pair $\left(\lambda_{1}, \lambda_{2}\right)$ with $\lambda_{1}<0,0<\lambda_{2}<1$ belongs to to $R^{r}(X, Y)$ if and only if for any $q_{Y}$ there exists $r_{X Y}$ with $r_{Y}=q_{Y}$ such that:

$$
\frac{1}{\lambda_{1}} D\left(r_{X} \| p_{X}\right)+\frac{1}{\lambda_{2}} D\left(q_{Y} \| p_{Y}\right) \geq D\left(r_{X Y} \| p_{X Y}\right)
$$

## Evaluation of (Reverse) Hypercontractivity Parameters

Hypercontractive Region Evaluation

Information Theory

- Related to determining extremal distributions in multiuser information theory


## Gray-Wyner Source Coding

Hypercontractive Region Evaluation


Figure 2: Gray-Wyner Source Coding Setting
Theorem 2.1 [Gray-Wyner 1974]
The optimal rate region $\mathscr{R}\left(p_{X Y}\right)$ is the set of rate triplets $\left(R_{0}, R_{1}, R_{2}\right)$ such that

$$
\begin{align*}
& R_{0} \geq I(X, Y ; V), \\
& R_{1} \geq H(X \mid V),  \tag{1}\\
& R_{2} \geq H(Y \mid V)
\end{align*}
$$

for some conditional pmf $p_{V \mid X Y}$ with $|\mathcal{V}| \leq|\mathcal{X}||\mathcal{Y}|+2$.

## Gray-Wyner Source Coding Setting

Hypercontractive Region Evaluation

Evaluation of the region: using $\left(\gamma_{1}, \gamma_{2}\right)$ weighted sum rates

$$
\begin{aligned}
& \min R_{0}+\gamma_{1} R_{1}+\gamma_{2} R_{2} \\
= & \min I(X Y ; V)+\gamma_{1} H(X \mid V)+\gamma_{2} H(Y \mid V) \\
= & H(X Y)+\mathfrak{K}\left[\gamma_{1} H(X)+\gamma_{2} H(Y)-H(X Y)\right]_{p_{X Y}}
\end{aligned}
$$

Observations [Beigi-Gohari 2015]:

- Tensorization of forward hypercontractivity $\Leftrightarrow$ Optimality of single letter expression of Gray-Wyner System
- $\left\{p_{X Y}: p_{X Y}\right.$ is $\left(\frac{1}{\gamma_{1}}, \frac{1}{\gamma_{2}}\right)$ forward hypercontractive $\} \equiv$ the set of extremal distributions $p_{X Y}$ for computing the lower convex envelope in the Gray-Wyner System


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## Main result 1: forward hypercontractive region

Binary Erasure Channel (BEC) with uniform input: [Nair-Wang 2016]
Consider a uniformly distributed binary valued $X$ passed through a BEC with erasure probability $\epsilon$ producing the ternary output $Y$. For $\lambda_{1}, \lambda_{2} \in(1, \infty)$,

- when $\epsilon-\frac{1}{2} \leq \frac{3}{2}\left(\lambda_{2}-1\right)$, the forward hypercontractive region for $(X, Y)$ is characterized by $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq 1-\epsilon$;
- When $\epsilon-\frac{1}{2}>\frac{3}{2}\left(\lambda_{2}-1\right)$, the forward hypercontractive region for $(X, Y)$ is strictly inside $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq 1-\epsilon$.


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Remarks:

- $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq 1-\epsilon$ is tight when $\epsilon \leq \frac{1}{2}$;
- $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq 1-\epsilon$ is tight when $\lambda_{2} \geq \frac{4}{3}$.

Forward hypercontractive region for BEC with uniform input
Define $\lambda_{2}^{\prime}:=\frac{\lambda_{2}}{\lambda_{2}-1}$, the Hölder conjugate of $\lambda_{2}$.
When $\epsilon=0.2$,


Figure 3: Forward hypercontractive region: $\epsilon=0.2$

Main result 2: reverse hypercontractive region

Binary Erasure Channel (BEC) with uniform input: [Nair-Wang 2017]
Consider a uniformly distributed binary valued $X$ passed through a BEC with erasure probability $\epsilon$ producing the ternary output $Y$. When $\lambda_{2}<0,(X, Y)$ is $\left(\lambda_{1}, \lambda_{2}\right)$ reverse hypercontractive if and only if

$$
\lambda_{1} \leq \frac{\ln 2}{\ln 2-\frac{\lambda_{2}-1}{\lambda_{2}} \ln \left[(1-\epsilon) 2^{\frac{1}{\lambda_{2}-1}}+\epsilon\right]}
$$

Remarks:

- The region $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq 1-\epsilon$ is not tight.

Reverse hypercontractive region for BEC with uniform input
Define $\lambda_{2}^{\prime}:=\frac{\lambda_{2}}{\lambda_{2}-1}$, the Hölder conjugate of $\lambda_{2}$.
When $\epsilon=0.2$,


Figure 4: Reverse hypercontractive region: $\epsilon=0.2$

Proof sketch for forward hypercontractive region

Case 1: $\lambda_{2} \geq 2$

- Mimic Janson's proof technique for BSC [Janson 1997]: Denote $\lambda_{2}^{\prime}:=\frac{\lambda_{2}}{\lambda_{2}-1}$, by Hölder's inequality, suffices to show that given $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right) \geq 1-\epsilon$,

$$
\|\mathrm{E}(f(X) \mid Y)\|_{\lambda_{2}^{\prime}} \leq\|f(X)\|_{\lambda_{1}}
$$

W.l.o.g let $f(0)=1-\delta, f(1)=1+\delta$, compare the coefficients of Taylor expansion around $\delta=0$ for both sides.

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W.l.o.g let $f(0)=1-\delta, f(1)=1+\delta$, compare the coefficients of Taylor expansion around $\delta=0$ for both sides.

- Works for binary input symmetric output channel with binary uniform inputs $X$ and $Y$ is obtained via a symmetric channel $W_{Y \mid X}$.

$$
W_{Y \mid X}(Y=i \mid X=1)=W_{Y \mid X}(Y=-i \mid X=-1)=p_{i}, \forall-K \leq i \leq K, K \in \mathbb{N}_{+}
$$

Proof sketch for forward hypercontractive region

Case 2: $1<\lambda_{2}<2$, denote the joint distribution of binary erasure channel with uniform input as $p_{X Y}^{B E C(\epsilon)}$.

- Needs to show when $\left(\lambda_{1}-1\right)\left(\lambda_{2}-1\right)=1-\epsilon$,

$$
\begin{aligned}
\max _{q_{X Y} \ll p_{X Y}^{B E C(\epsilon)}} & \frac{1}{\lambda_{1}} D\left(q_{X} \| p_{X}^{B E C(\epsilon)}\right)+\frac{1}{\lambda_{2}} D\left(q_{X} \| p_{Y}^{B E C(\epsilon)}\right)-D\left(q_{X Y} \| p_{X Y}^{B E C(\epsilon)}\right) \\
& = \begin{cases}0 & \text { if } \epsilon-\frac{1}{2} \leq \frac{3}{2}\left(\lambda_{2}-1\right) \\
>0 & \text { otherwise }\end{cases}
\end{aligned}
$$

- Non-convex optimization problem: Maximum happens in the interior.
- Trivial stationary point $q_{X Y}=p_{X Y}^{B E C(\epsilon)}$.

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$$

- Non-convex optimization problem: Maximum happens in the interior.
- Trivial stationary point $q_{X Y}=p_{X Y}^{B E C(\epsilon)}$.
- Proof idea: the stationary points of this 3 -variable function are restricted on a 1 -parameter path.

Proof sketch for forward hypercontractive region
Case 2: $1<\lambda_{2}<2$, set $1-\delta=\frac{2 q_{0 E}}{q_{0 E}+q_{1 E}}$, from the first order conditions, any (strictly) interior stationary points can be parameterized in

$$
\begin{aligned}
q_{X Y} & =\left[q_{00}, q_{0 E}, q_{1 E}, q_{11}\right] \\
& =\left[\frac{(1-\delta)^{\lambda_{2}^{\prime}}(1-\epsilon)}{A}, \frac{\epsilon(1-\delta)}{A}, \frac{\epsilon(1+\delta)}{A}, \frac{(1-\epsilon)(1+\delta)^{\lambda_{2}^{\prime}}}{A}\right]
\end{aligned}
$$

where $A=2 \epsilon+(1-\epsilon)\left[(1+\delta)^{\lambda_{2}^{\prime}}+(1-\delta)^{\lambda_{2}^{\prime}}\right]$ is the normalizing constant and $\delta$ satisfies that

$$
(1-\epsilon)(1-\delta)^{\frac{\epsilon}{\lambda_{2}-1}}+\epsilon(1-\delta)^{\frac{\epsilon-1}{\lambda_{2}-1}}=(1-\epsilon)(1+\delta)^{\frac{\epsilon}{\lambda_{2}-1}}+\epsilon(1+\delta)^{\frac{\epsilon-1}{\lambda_{2}-1}}
$$

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(1-\epsilon)(1-\delta)^{\frac{\epsilon}{\lambda_{2}-1}}+\epsilon(1-\delta)^{\frac{\epsilon-1}{\lambda_{2}-1}}=(1-\epsilon)(1+\delta)^{\frac{\epsilon}{\lambda_{2}-1}}+\epsilon(1+\delta)^{\frac{\epsilon-1}{\lambda_{2}-1}}
$$

- When $\left(\epsilon-\frac{1}{2}\right) \leq \frac{3}{2}\left(\lambda_{2}-1\right)$ and $\lambda_{2} \in(1,2)$, this equation has only one root at $\delta=0$, implying only one stationary point $q_{X Y}=p_{X Y}^{B E C(\epsilon)}$;


## Proof sketch for forward hypercontractive region

Case 2: $1<\lambda_{2}<2$, set $1-\delta=\frac{2 q_{0 E}}{q_{0 E}+q_{1 E}}$, from the first order conditions, any (strictly) interior stationary points can be parameterized in

$$
\begin{aligned}
q_{X Y} & =\left[q_{00}, q_{0 E}, q_{1 E}, q_{11}\right] \\
& =\left[\frac{(1-\delta)^{\lambda_{2}^{\prime}}(1-\epsilon)}{A}, \frac{\epsilon(1-\delta)}{A}, \frac{\epsilon(1+\delta)}{A}, \frac{(1-\epsilon)(1+\delta)^{\lambda_{2}^{\prime}}}{A}\right]
\end{aligned}
$$

where $A=2 \epsilon+(1-\epsilon)\left[(1+\delta)^{\lambda_{2}^{\prime}}+(1-\delta)^{\lambda_{2}^{\prime}}\right]$ is the normalizing constant and $\delta$ satisfies that

$$
(1-\epsilon)(1-\delta)^{\frac{\epsilon}{\lambda_{2}-1}}+\epsilon(1-\delta)^{\frac{\epsilon-1}{\lambda_{2}-1}}=(1-\epsilon)(1+\delta)^{\frac{\epsilon}{\lambda_{2}-1}}+\epsilon(1+\delta)^{\frac{\epsilon-1}{\lambda_{2}-1}}
$$

- When $\left(\epsilon-\frac{1}{2}\right) \leq \frac{3}{2}\left(\lambda_{2}-1\right)$ and $\lambda_{2} \in(1,2)$, this equation has only one root at $\delta=0$, implying only one stationary point $q_{X Y}=p_{X Y}^{B E C(\epsilon)}$;
- When $\left(\epsilon-\frac{1}{2}\right)>\frac{3}{2}\left(\lambda_{2}-1\right)$, Taylor series expansion around $\delta=0$ gives that

$$
\frac{1}{\lambda_{1}} D\left(q_{X} \| p_{X}^{B E C(\varepsilon)}\right)+\frac{1}{\lambda_{2}} D\left(q_{Y} \| p_{Y}^{B E C(\varepsilon)}\right)-D\left(q_{X Y} \| p_{X Y}^{B E C(\varepsilon)}\right)>0
$$

Proof sketch for reverse hypercontractive region
When $\lambda_{2}<0$, need to determine $\left(\lambda_{1}, \lambda_{2}\right)$ such that

$$
\min _{q_{X}} \max _{r_{X Y}} \frac{1}{\lambda_{1}} D\left(q_{X} \| p_{X}^{B E C(\epsilon)}\right)+\frac{1}{\lambda_{2}} D\left(q_{Y} \| p_{Y}^{B E C(\epsilon)}\right)-D\left(r_{X Y} \| p_{X Y}^{B E C(\epsilon)}\right) \geq 0
$$

Write $q_{X}(0)=x, r_{X Y}(0,0)=r, r_{X Y}(1,1)=s$ and denote above 3-variable function as $f(x, r, s)$. Define, for $x \in[0,1]$

$$
g(x):=\max _{r, s: r \in[0, x], s \in[0,1-x]} f(x, r, s) .
$$

Wish to determine $\left(\lambda_{1}, \lambda_{2}\right)$ (with $\left.\lambda_{2}<0\right)$ such that $g(x) \geq 0, \forall x \in[0,1]$.

Proof sketch for reverse hypercontractive region
When $\lambda_{2}<0$, need to determine $\left(\lambda_{1}, \lambda_{2}\right)$ such that

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Wish to determine $\left(\lambda_{1}, \lambda_{2}\right)$ (with $\left.\lambda_{2}<0\right)$ such that $g(x) \geq 0, \forall x \in[0,1]$. Easy direction: From above, we require $g(0) \geq 0$. This implies that

$$
\lambda_{1} \leq \frac{\ln 2}{\ln 2-\frac{\lambda_{2}-1}{\lambda_{2}} \ln \left[(1-\epsilon) 2^{\frac{1}{\lambda_{2}-1}}+\epsilon\right]}
$$

## Proof sketch for reverse hypercontractive region

When $\lambda_{2}<0$, need to determine $\left(\lambda_{1}, \lambda_{2}\right)$ such that

$$
\min _{q_{X}} \max _{r_{X Y}} \frac{1}{\lambda_{1}} D\left(q_{X} \| p_{X}^{B E C(\epsilon)}\right)+\frac{1}{\lambda_{2}} D\left(q_{Y} \| p_{Y}^{B E C(\epsilon)}\right)-D\left(r_{X Y} \| p_{X Y}^{B E C(\epsilon)}\right) \geq 0
$$

Write $q_{X}(0)=x, r_{X Y}(0,0)=r, r_{X Y}(1,1)=s$ and denote above 3-variable function as $f(x, r, s)$. Define, for $x \in[0,1]$

$$
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$$

Wish to determine $\left(\lambda_{1}, \lambda_{2}\right)$ (with $\lambda_{2}<0$ ) such that $g(x) \geq 0, \forall x \in[0,1]$.
Easy direction: From above, we require $g(0) \geq 0$. This implies that

$$
\lambda_{1} \leq \frac{\ln 2}{\ln 2-\frac{\lambda_{2}-1}{\lambda_{2}} \ln \left[(1-\epsilon) 2^{\frac{1}{\lambda_{2}-1}}+\epsilon\right]}
$$

Non-trivial direction: we show that

- $g(x)$ is symmetric along $x=\frac{1}{2}$. (Easy - by symmetry of the $(X, Y)$-distribution)
- $g(x)$ is convex at $x=\frac{1}{2}$ and $g^{\prime}\left(\frac{1}{2}\right)=0, g\left(\frac{1}{2}\right)=0$. (Easy)
- $g(x)$ has only one stationary point, i.e., $g^{\prime}(x)=0$, between $\left(0, \frac{1}{2}\right)$. (Needs to use the 1-parameter path)


## Related Open Questions

To conclude,
(1) In our proofs, local analysis suffices to compute the hypercontractive region.
(2) The critical behavior happens at the boundary for reverse hypercontractivity.

## Related Open Questions

To conclude,
(1) In our proofs, local analysis suffices to compute the hypercontractive region.
(2) The critical behavior happens at the boundary for reverse hypercontractivity.

How to determine hypercontractive parameters for a general joint distribution?

- In other words, does the functional

$$
\frac{1}{\lambda_{1}} H(X)+\frac{1}{\lambda_{2}} H(Y)-H(X Y)-E_{p_{X Y}}\left(d_{X Y}\right)
$$

have nice geometric properties (or low dimensional reparametrizations) that allow such local arguments to work?

- If so, can we devise an algorithm to efficiently approximate the hypercontractivity parameters?


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- Main Results on Hypercontractivity
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- Alternative Proofs to Quadratic Gaussian CEO Problem and Distributed Source Coding Problem
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## Lossless source coding with two helpers



Figure 5: Lossless source coding with two helpers

- The optimal rate region is unknown for a general $p_{X Y Z}$.
- Consider the projection $R_{0}=0$ :

Lossless source coding with two helpers


Figure 5: Lossless source coding with two helpers

- The optimal rate region is unknown for a general $p_{X Y Z}$.
- Consider the projection $R_{0}=0$ :

Slepian-Wolf region [Slepian-Wolf 1973]
When $p_{X Y Z}$ satisfies that $Z=(X, Y)$, the optimal rate region is given by (achieved by random binning)

$$
\begin{aligned}
R_{1} & \geq H(X \mid Y) \\
R_{2} & \geq H(Y \mid X) \\
R_{1}+R_{2} & \geq H(X Y)
\end{aligned}
$$

Lossless source coding with two helpers


Figure 5: Lossless source coding with two helpers

- The optimal rate region is unknown for a general $p_{X Y Z}$.
- Consider the projection $R_{0}=0$ :

Körner-Marton region [Körner-Marton 1979]
When $X, Y$ binary and $p_{X Y Z}$ satisfies that $Z=X \oplus Y$, a rate pair $\left(R_{1}, R_{2}\right)$ is achievable by random linear codes if

$$
\begin{aligned}
& R_{1} \geq H(Z) \\
& R_{2} \geq H(Z)
\end{aligned}
$$

The optimal rate region for $Z=X \oplus Y$ is unknown for a general $p_{X Y}$. This is referred to as Körner and Marton's modulo two sum problem.

## Known results on the optimal rate region

Exercise 16.23 in [Csiszár-Körner 2011] ${ }^{1}$
When $p_{X Y}$ satisfies that $H(Z) \geq \min \{H(X), H(Y)\}$, the optimal rate region for $Z=X \oplus Y$ in $G F(2)$ is given by Slepian-Wolf region:

$$
\begin{aligned}
R_{1} & \geq H(X \mid Y), \\
R_{2} & \geq H(Y \mid X), \\
R_{1}+R_{2} & \geq H(X Y) .
\end{aligned}
$$

${ }^{1}$ I. Csiszár and J. Körner, Information theory: Coding theorems for discrete memoryless systems

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Theorem 1 in [Körner-Marton 1979]
When $p_{X Y}$ follows binary symmetric channel with uniform inputs, the optimal rate region for $Z=X \oplus Y$ in $G F(2)$ is given by Körner-Marton region:

$$
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$$
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& R_{2} \geq H(Z) .
\end{aligned}
$$

This part: more distributions $p_{X Y}$ are discovered for optimality of Slepian-Wolf coding scheme and Körner-Marton coding scheme on weighted sum rate.
${ }^{1}$ I. Csiszár and J. Körner, Information theory: Coding theorems for discrete memoryless systems

## Achievable region and lower bound

## Ahlswede-Han achievable region: [Ahlswede-Han 1973]

When $Z=X \oplus Y$, a rate pair $\left(R_{1}, R_{2}\right)$ is achievable via a combination of random linear codes and random binning if

$$
\begin{aligned}
R_{1} & \geq I(U ; X \mid V)+H(Z \mid U V) \\
R_{2} & \geq I(V ; Y \mid U)+H(Z \mid U V) \\
R_{1}+R_{2} & \geq I(U V ; X Y)+2 H(Z \mid U V)
\end{aligned}
$$

for some $U$ and $V$ that satisfy the Markov chain $U \rightarrow X \rightarrow Y \rightarrow V$.

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$$

for some $U$ and $V$ that satisfy the Markov chain $U \rightarrow X \rightarrow Y \rightarrow V$.

Cut-set lower bound: [Körner-Marton 1979]
Any achievable rate pair $\left(R_{1}, R_{2}\right)$ for the modulo sum problem must satisfy

$$
\begin{aligned}
R_{1} & \geq H(Z \mid Y)=H(X \mid Y) \\
R_{2} & \geq H(Z \mid X)=H(Y \mid X) \\
R_{1}+R_{2} & \geq H(Z)
\end{aligned}
$$

## Main result: A lower bound

A lower bound on modulo sum problem [Nair-Wang 2020]
Any achievable rate pair $\left(R_{1}, R_{2}\right)$ for the modulo sum problem must satisfy the following constraints for any $\lambda \geq 1$ :

$$
\begin{aligned}
& R_{1}+\lambda R_{2} \geq H(X Y)+\min _{U \rightarrow X \rightarrow Y} \lambda H(Z \mid U)-H(Y \mid U) \\
& \lambda R_{1}+R_{2} \geq H(X Y)+\min _{V \rightarrow Y \rightarrow X} \lambda H(Z \mid V)-H(X \mid V)
\end{aligned}
$$

Remark: From [Nair 2013]

$$
\min _{U \rightarrow X \rightarrow Y} \lambda H(Z \mid U)-H(Y \mid U)=-\left.\mathfrak{C}_{q_{X}}[H(Y)-\lambda H(Z)]\right|_{p(x)},
$$

where $\left.\mathfrak{C}_{x}[f]\right|_{x_{0}}$ denotes the upper concave envelope of the function $f(x)$ with respect to $x$ evaluated at $x=x_{0}$.

## Proof sketch

For $\lambda \geq 1$, any "good" sequence of codes will require that

$$
\begin{aligned}
& n\left(R_{1}+\lambda R_{2}\right)+n(1+\lambda) \varepsilon_{n} \\
& \geq I\left(M_{1} M_{2} ; X^{n} Y^{n}\right)+(\lambda-1) H\left(M_{2} \mid M_{1}\right)+(1+\lambda) H\left(Z^{n} \mid M_{1} M_{2}\right)
\end{aligned}
$$

## Proof sketch

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$$
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& =H\left(X^{n} Y^{n}\right)-H\left(X^{n} Y^{n} M_{1} M_{2}\right)+(\lambda-1) H\left(M_{1} M_{2}\right)-(\lambda-1) H\left(M_{1}\right) \\
& \quad \quad+(1+\lambda) H\left(Z^{n} M_{1} M_{2}\right)-\lambda H\left(M_{1} M_{2}\right) \\
& \stackrel{(a)}{=} H\left(X^{n} Y^{n}\right)+\lambda H\left(Z^{n} M_{1} M_{2}\right)+H\left(Z^{n} M_{1} M_{2}\right)-H\left(Z^{n} Y^{n} M_{1} M_{2}\right)-H\left(M_{1} M_{2}\right) \\
& \quad \quad-(\lambda-1) H\left(M_{1}\right) \\
& \stackrel{(b)}{=} H\left(X^{n} Y^{n}\right)+\lambda H\left(Z^{n} M_{1}\right)+\underline{\lambda H\left(M_{2} \mid M_{1} Z^{n}\right)}-H\left(Y^{n} M_{1} M_{2}\right)+\underline{I\left(Z^{n} ; Y^{n} \mid M_{1} M_{2}\right)} \\
& \quad \quad-(\lambda-1) H\left(M_{1}\right) \\
& \geq n H(X Y)+\lambda H\left(Z^{n} M_{1}\right)-\underset{\sim}{H\left(Y^{n} M_{1}\right)}-(\lambda-1) H\left(M_{1}\right) \\
& =n H(X Y)+\lambda H\left(Z^{n} \mid M_{1}\right)-H\left(Y^{n} \mid M_{1}\right)
\end{aligned}
$$

- Step (a) uses $H\left(X^{n} Y^{n} M_{1} M_{2}\right)=H\left(Z^{n} X^{n} Y^{n} M_{1} M_{2}\right)=H\left(Z^{n} Y^{n} M_{1} M_{2}\right)$.
- Step (b) uses $I\left(Z^{n} ; Y^{n} \mid M_{1} M_{2}\right)=H\left(Z^{n} M_{1} M_{2}\right)+H\left(Y^{n} M_{1} M_{2}\right)-H\left(M_{1} M_{2}\right)-$ $H\left(Z^{n} Y^{n} M_{1} M_{2}\right)$.


## Sinlge-letterize the lower bound

Lemma 3.1: Körner-Marton identity (4.14) in [Körner-Marton 1977]
Let $\lambda \geq 1$ and let $\left(X^{n}, Y^{n}\right)$ be i.i.d distributed according to $p(x, y)$ where $X, Y$ take values in a finite field. Let $Z^{n}$ be obtained as $Z_{i}=X_{i} \oplus Y_{i}, i=1, . ., n$, i.e. the component-wise modulo sum on the field. Then for any $\lambda \geq 1$ the following holds:

$$
\begin{aligned}
& \hat{U}: \hat{U} \rightarrow X^{n} \rightarrow Y^{n} \\
& \quad=n\left(\min _{U: U \rightarrow X \rightarrow Y} \lambda H(Z \mid U)-H(Y \mid U)\right) .
\end{aligned}
$$

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$$
\begin{aligned}
& \hat{U}: \hat{U} \rightarrow X^{n} \rightarrow Y^{n} \\
& \quad=n\left(\min _{U: U \rightarrow X \rightarrow Y} \lambda H\left(Z^{n} \mid \hat{U}\right)-H\left(Y^{n} \mid \hat{U}\right)\right. \\
& \quad=n)-H(Y \mid U)) .
\end{aligned}
$$

- Evaluating the weighted sum rate lower bounds are non-convex optimization problems:

$$
\begin{aligned}
& R_{1}+\lambda R_{2} \geq H(X Y)+\min _{U \rightarrow X \rightarrow Y} \lambda H(Z \mid U)-H(Y \mid U) \\
& \lambda R_{1}+R_{2} \geq H(X Y)+\min _{V \rightarrow Y \rightarrow X} \lambda H(Z \mid V)-H(X \mid V)
\end{aligned}
$$

- Next: When will this lower bound match Körner-Marton region or Slepian-Wolf region in terms of weighted sum rates?


## Application to binary alphabets $\mathrm{GF}(2)$ : Previous results

Notation: $P(X=0)=x, P(Y=0 \mid X=0)=c, P(Y=1 \mid X=1)=d$.
Previous results: Optimal weighted sum rates $R_{1}+\lambda R_{2}$.
When $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right) \leq 0(\Leftrightarrow H(Z) \geq H(Y)), \quad$ When $c=d$,



Figure 7: When is Körner-Marton region optimal

## Application to binary alphabets GF(2): New Results

Notation: $P(X=0)=x, P(Y=0 \mid X=0)=c, P(Y=1 \mid X=1)=d$.

Our work: When $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right)>0(\Leftrightarrow H(Z)<H(Y))$,

Example 1: $c=0.9, d=0.6$


## Application to binary alphabets GF(2): New Results

Notation: $P(X=0)=x, P(Y=0 \mid X=0)=c, P(Y=1 \mid X=1)=d$.

Our work: When $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right)>0(\Leftrightarrow H(Z)<H(Y))$,

Example 2: $c=0.7, d=0.6$

## Comparison of the bounds

In [Ahlswede-Han 1983], Ahlswede and Han chose the following $p_{X Y}$ given by


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## Quadratic Gaussian CEO Problem



Figure 8: generalized CEO distributed source coding

Distortion criterion: $\lim \sup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(X_{i}, \hat{X}_{i}\right)\right) \leq D$.

- Quadratic Gaussian CEO problem: $d\left(X_{i}, \hat{X}_{i}\right)=\left(X_{i}-\hat{X}_{i}\right)^{2}$; $Y_{1}=X+Z_{1}, Z_{1} \perp X, Z_{1} \sim N\left(0, N_{1}\right) ; Y_{2}=X+Z_{2}, Z_{2} \perp X, Z_{2} \sim N\left(0, N_{2}\right)$.
- Berger-Tung coding scheme [Berger 1978; Tung 1978; Prabhakaran-TseRamachandran 2004] is shown to be optimal by Oohama [Oohama 2005].


## Quadratic Gaussian CEO Problem

## A lower bound to generalized CEO problem

Consider previous generalized CEO distributed source coding on $X, Y_{1}, Y_{2}$ satisfying that
$Y_{1} \rightarrow X \rightarrow Y_{2}$ with the distortion criterion $\limsup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(X_{i}, \hat{X}_{i}\right)\right) \leq D$. For any $\lambda \geq 1$, any
achievable triple $\left(R_{1}, R_{2}, D\right)$ must satisfy that

$$
\begin{aligned}
& R_{1}+\lambda R_{2} \geq H\left(X Y_{1}\right)+\lambda H\left(Y_{2} \mid X\right)+(\lambda-1) \max \left\{H\left(X \mid U_{1} W Q\right)-H(X \mid \hat{X} Q), 0\right\} \\
&-H(X \mid \hat{X} Q)-H\left(Y_{1} \mid X U_{1} W Q\right)-\lambda H\left(Y_{2} \mid X U_{2} W Q\right) \\
& R_{2}+\lambda R_{1} \geq H\left(X Y_{2}\right)+\lambda H\left(Y_{1} \mid X\right)+(\lambda-1) \max \left\{H\left(X \mid U_{2} W Q\right)-H(X \mid \hat{X} Q), 0\right\} \\
&-H(X \mid \hat{X} Q)-H\left(Y_{2} \mid X U_{2} W Q\right)-\lambda H\left(Y_{1} \mid X U_{1} W Q\right)
\end{aligned}
$$

subject to the constraints

$$
\begin{aligned}
& U_{1} \leftarrow Q W Y_{1} \leftarrow Q W X \rightarrow Q W Y_{2} \rightarrow U_{2} \\
& Q W \perp X Y_{1} Y_{2} \\
& \hat{X} \leftarrow Q W U_{1} U_{2} \rightarrow X Y_{1} Y_{2} \\
& E[d(X, \hat{X})] \leq D
\end{aligned}
$$

Proof sketch: $W_{i}=X^{n / i}, U_{1 i}=M_{1} Y_{1}^{i-1}, U_{2 i}=M_{2} Y_{2}^{i-1} . Q$ is the uniform distribution over $i=1, \cdots, n$. This is in a similar spirit as the lower bound [Wagner-Anantharam 2008].

## Quadratic Gaussian CEO Problem

## A lower bound to generalized CEO problem

Consider previous generalized CEO distributed source coding on $X, Y_{1}, Y_{2}$ satisfying that
$Y_{1} \rightarrow X \rightarrow Y_{2}$ with the distortion criterion $\limsup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(X_{i}, \hat{X}_{i}\right)\right) \leq D$. For any $\lambda \geq 1$, any
achievable triple $\left(R_{1}, R_{2}, D\right)$ must satisfy that

$$
\begin{aligned}
R_{1}+\lambda R_{2} \geq & H\left(X Y_{1}\right)+\lambda H\left(Y_{2} \mid X\right)+(\lambda-1) \max \left\{H\left(X \mid U_{1} W Q\right)-H(X \mid \hat{X} Q), 0\right\} \\
& -H(X \mid \hat{X} Q)-H\left(Y_{1} \mid X U_{1} W Q\right)-\lambda H\left(Y_{2} \mid X U_{2} W Q\right) \\
R_{2}+\lambda R_{1} \geq & H\left(X Y_{2}\right)+\lambda H\left(Y_{1} \mid X\right)+(\lambda-1) \max \left\{H\left(X \mid U_{2} W Q\right)-H(X \mid \hat{X} Q), 0\right\} \\
& -H(X \mid \hat{X} Q)-H\left(Y_{2} \mid X U_{2} W Q\right)-\lambda H\left(Y_{1} \mid X U_{1} W Q\right)
\end{aligned}
$$

subject to the constraints

$$
\begin{aligned}
& U_{1} \leftarrow Q W Y_{1} \leftarrow Q W X \rightarrow Q W Y_{2} \rightarrow U_{2} \\
& Q W \perp X Y_{1} Y_{2} \\
& \hat{X} \leftarrow Q W U_{1} U_{2} \rightarrow X Y_{1} Y_{2} \\
& E[d(X, \hat{X})] \leq D .
\end{aligned}
$$

Rotation techniques in [Geng-Nair 2014] can show that Gaussian $U_{1}, U_{2}$ and constant $Q, W$ minimizes above weighted sum rate lower bound.

## Quadratic Gaussian Distributed Source Coding



Figure 9: Generalized Distributed Source Coding with auxiliary source structure
$\limsup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(Y_{1 i}, \hat{Y}_{1 i}\right)\right) \leq D_{1}, \lim \sup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(Y_{2 i}, \hat{Y}_{2 i}\right)\right) \leq D_{2}$.

- Quadratic Gaussian distributed source coding problem: $d\left(X_{i}, \hat{X}_{i}\right)=\left(X_{i}-\hat{X}_{i}\right)^{2}$,
$\left(Y_{1}, Y_{2}\right) \sim N\left(\overrightarrow{0},\left[\begin{array}{ll}1 & \rho \\ \rho & 1\end{array}\right]\right)$.
- Berger-Tung coding scheme [Berger 1978; Tung 1978; Prabhakaran-TseRamachandran 2004] is shown to be optimal by [Wagner-Tavildar-Viswanath 2008].
- Assume there exists some auxiliary source $X$ such that $Y_{1} \leftarrow X \rightarrow Y_{2}$.


## Quadratic Gaussian Distributed Source Coding

## A lower bound to generalized distributed source coding

Consider the generalized quadratic distributed source coding on 2-DMS $\left(Y_{1}, Y_{2}\right)$ with the distortion criterion $\lim \sup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(Y_{1 i}, \hat{Y}_{1 i}\right)\right) \leq D_{1}$ and $\lim \sup _{n \rightarrow \infty} \mathrm{E}\left(\frac{1}{n} \sum_{i=1}^{n} d\left(Y_{2 i}, \hat{Y}_{2 i}\right)\right) \leq D_{2}$. Assume there exists some auxiliary source $X$ such that $Y_{1}$ and $Y_{2}$ are obtained by passing $X$ through some discrete memoryless channel $W_{1}$ and $W_{2}$ respectively. For any $\lambda \geq 1$, any achievable triple ( $R_{1}, R_{2}, D_{1}, D_{2}$ ) must satisfy that

$$
\begin{aligned}
R_{1}+\lambda R_{2} \geq & H\left(X Y_{1}\right)+\lambda H\left(Y_{2} \mid X\right)-H\left(X \mid \hat{Y}_{1} \hat{Y}_{2} Q\right)-H\left(Y_{1} \mid X U_{1} Q W\right) \\
& +(\lambda-1) \max \left\{H\left(X \mid U_{1} Q W\right)-H\left(X \mid \hat{Y}_{1} \hat{Y}_{2} Q\right), 0\right\}-\lambda H\left(Y_{2} \mid X U_{2} Q W\right) \\
R_{2}+\lambda R_{1} \geq & H\left(X Y_{2}\right)+\lambda H\left(Y_{1} \mid X\right)-H\left(X \mid \hat{Y}_{1} \hat{Y}_{2} Q\right)-H\left(Y_{2} \mid X U_{2} Q W\right) \\
& +(\lambda-1) \max \left\{H\left(X \mid U_{2} Q W\right)-H\left(X \mid \hat{Y}_{1} \hat{Y}_{2} Q\right), 0\right\}-\lambda H\left(Y_{1} \mid X U_{1} Q W\right)
\end{aligned}
$$

subject to the constraint

$$
\begin{aligned}
& U_{1} \leftarrow Q W Y_{1} \leftarrow Q W X \rightarrow Q W Y_{2} \rightarrow U_{2} \\
& Q W \perp X Y_{1} Y_{2} \\
& \hat{Y}_{1} \hat{Y}_{2} \leftarrow Q W U_{1} U_{2} \rightarrow X Y_{1} Y_{2} \\
& \mathrm{E}\left[d\left(Y_{1}, \hat{Y}_{1}\right)\right] \leq D_{1}, \mathrm{E}\left[d\left(Y_{2}, \hat{Y}_{2}\right)\right] \leq D_{2}
\end{aligned}
$$

This is also in a similar spirit as the lower bound [Wagner-Anantharam 2008].

## Outline

(1) Hypercontractive Region Evaluation

- Introduction to Hypercontractivity
- Main Results on Hypercontractivity
(2) Lower Bounds on Distributed Source Coding
- Körner and Marton's Modulo Two Sum Problem
- Alternative Proofs to Quadratic Gaussian CEO Problem and Distributed Source Coding Problem
(3) Log-Convexity of Fisher Information
- Motivations
- Proof to log-convexity of Fisher information


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## Motivation 1: Non-convex optimization problem

A non-convex optimization problem
Let $W_{Y \mid X}$ denote a channel that maps input random variable $X$ with distribution $\mu_{X}$ into the output random variable $Y$ with distribution $\mu_{Y}$. Consider the non-convex optimization problem, that is, computing the maximum over $\mu_{X}$ of

$$
F_{\lambda}\left(\mu_{X}\right):=\lambda H(X)-H(Y)
$$

where $0 \leq \lambda \leq 1$ is some fixed constant.

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$$

where $0 \leq \lambda \leq 1$ is some fixed constant.

Mrs Gerber's Lemma [Wyner-Ziv 1973]
When the channel $W_{Y \mid X}$ is the binary symmetric channel with flipping probability $p$, under the reparametrization of $\mu_{X}$, defined by $\mu_{X}(u)=H_{2}^{-1}(u)$,

$$
F_{\lambda}(u)=\lambda u-H_{2}\left(p * H_{2}^{-1}(u)\right) .
$$

is concave in $u$ for any $\lambda$. Here $a * b:=a(1-b)+(1-a) b$.
Question: Is there an analogous result in the additive Gaussian noise channel setting that is, $Y=X+W$ where $W \sim N\left(0, \sigma^{2}\right)$ ?

## Motivation 1: Non-convex optimization problem

- In the continuous world, to make moving direction limited in one dimension, we assume that

$$
\begin{aligned}
X_{t} & :=X+\sqrt{t} Z, t>0, Z \sim N(0,1) \\
Y_{t} & :=X_{t}+W, W \sim N\left(0, \sigma^{2}\right)
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\end{aligned}
$$

- $\mu_{t}^{X}$ : the probability density function of $X+\sqrt{t} Z . \mu_{t}^{X}$ satisfies the heat flow equation: $\frac{\partial \mu_{t}^{X}}{\partial t}=\frac{1}{2} \frac{\partial^{2} \mu_{t}^{X}}{\partial x^{2}}$ with initial condtion $\mu_{0}^{X}(x) \equiv f(x)$, where $f(x)$ is the probability density function of $X$.
- The differential entropy $h(X):=-\int_{\mathbb{R}} f(x) \ln f(x) d x$.


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- The differential entropy $h(X):=-\int_{\mathbb{R}} f(x) \ln f(x) d x$.
- Want a parametrization $t=\phi(u)$ such that $h(X+\sqrt{\phi(u)} Z)$ is linear in $u$ and the output entropy, $h\left(\mu_{Y}\right)=h(X+\sqrt{\phi(u)} Z+W)$ is convex in $u$. A bit of algebra immediately shows that this question is equivalent to asking whether the Fisher information

$$
I\left(\mu_{t}^{X}\right):=\int_{\mathbb{R}}\left(\frac{\partial}{\partial x} \mu_{t}^{X}(x)\right)^{2} \mu_{t}^{X}(x) d x
$$

is log-convex in $t$, for all random variables $X$.

Motivation 2: Completely monontone and log-convexity

- Let $X$ be a random variable with a finite variance $P$. Let $g_{X}^{(0)}(t):=h\left(\mu_{t}^{X}\right)$, $g_{X}^{(k)}(t):=\frac{\partial^{k}}{\partial t^{k}} h\left(\mu_{t}^{X}\right)$. De Bruijin's identity tells that

$$
I\left(\mu_{t}^{X}\right)=2 \frac{\partial}{\partial t} h\left(\mu_{t}^{X}\right)=2 g_{X}^{(1)}(t)
$$

- Let $Z \sim N(0, P)$. In Section 12 of [McKean 1966], McKean observes that for any $t \geq 0, g_{Z}^{(0)}(t) \geq g_{X}^{(0)}(t) \geq 0, g_{Z}^{(1)}(t) \leq g_{X}^{(1)}(t) \leq 0$, and $g_{Z}^{(2)}(t) \geq g_{X}^{(2)}(t) \geq 0$. Therefore he conjectured that

Mckean's conjecture [McKean 1966]

$$
\forall X, \forall t \geq 0,(-1)^{k} g_{Z}^{(k)}(t) \geq(-1)^{k} g_{X}^{(k)}(t) \geq 0, \forall k \geq 3
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$$

- In [Cheng-Geng 2015], $g_{X}^{(3)}(t) \geq 0$, and $g_{X}^{(4)}(t) \leq 0$ for any $t \geq 0$ are established. They made a weaker conjecutre that $(-1)^{k} g_{X}^{(k)}(t) \geq 0$. In other words, $I\left(\mu_{t}^{X}\right)=2 g_{X}^{(1)}(t)$ is a completely monotone function of $t$, for all $X$.


## Motivation 2: Completely monontone and log-convexity

An alternate characterization of completely monotone function:

## Bernstein's theorem

Let $g(t):[0, \infty) \rightarrow[0, \infty)$ be a continuous and infinitely differentiable function. The following are equivalent:

- $g$ is completely monotone: $\forall n \in \mathbb{N}, \forall t>0,(-1)^{n} g^{(n)}(t) \geq 0$;
- $g$ is the Laplace transform of a finite Borel measure $\nu$ in $\mathbb{R}_{+}$:

$$
\forall x \in \mathbb{R}_{+}, g(x)=\int_{0}^{\infty} e^{-x t} d \nu(t)
$$

- Via this theorem, one can show that any completely monotone function $g(t)$ is log-convex with respect to $t$, see [Fink 1982].
- If $I\left(\mu_{t}^{X}\right)$ is a completely monotone function with respect to $t$, then $\ln I\left(\mu_{t}^{X}\right)$ is convex with respect to $t$.
This part: We established that $I\left(\mu_{t}^{X}\right)$ is log-convex in $t$, thus resolving affirmatively
Conjecture 2 in [Cheng-Geng 2015].


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## Notations and Previous Results

Proof techniques:

- The ideas and techiniques starts from a short proof to the "concavity of entropy power" (Costa's EPI) by C. Villani [Villani-2000], which is in turn motivated by calculations of Bakry and Emery [Bakry-Emery 1985].
- Later, [Cheng-Geng 2015] and [Zhang-Anantharam-Geng 2018] followed the work and developed these tools and notations.


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Notations:

- $v(x):=\ln \mu_{t}^{X}(x), t>0$, and $v_{k}(x):=\frac{\partial^{k} \ln \mu_{t}^{X}(x)}{\partial x^{k}}, k \in \mathbb{Z}_{+}$,
- $\langle\varphi\rangle:=\int_{\mathbb{R}} \varphi \mu_{t}^{X}(x) d x$

Key idea: Under these notations, our problems can be rewritten as inequalities in terms of $\left\langle\prod_{i=1}^{r} v_{k_{i}}^{m_{i}}\right\rangle$, where $r, m_{i}, k_{i} \in \mathbb{Z}_{+}$.

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Integration by parts formula, Lemma 3 in [Zhang-Anantharam-Geng 2018]
For $k \geq 2$, let $\varphi(x)$ be any "reasonably smooth" function.

$$
\left\langle\varphi v_{k}+\varphi v_{1} v_{k-1}+\frac{\partial \varphi}{\partial x} v_{k-1}\right\rangle=0
$$

- $\varphi$ could be chosen in the form of $\prod_{i=1}^{r} v_{k_{i}}^{m_{i}}(x)$.
- This gives the linear dependence relationships among the terms $\left\langle\prod_{i=1}^{r} v_{k_{i}}^{m_{i}}\right\rangle$.


## Villani's proof to Costa's EPI

Fisher information and its derivatives
For $t>0$, Fisher information $I\left(\mu_{t}^{X}\right)$ and its derivatives up to second order are:

$$
\begin{aligned}
I\left(\mu_{t}^{X}\right) & =\left\langle v_{1}^{2}\right\rangle \\
\frac{d}{d t} I\left(\mu_{t}^{X}\right) & =-\left\langle v_{2}^{2}\right\rangle, \\
\frac{d^{2}}{d t^{2}} I\left(\mu_{t}^{X}\right) & =\left\langle v_{3}^{2}+2 v_{1}^{2} v_{2}^{2}+4 v_{1} v_{2} v_{3}\right\rangle .
\end{aligned}
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Costa's EPI in scalar case, [Costa 1985]
For any random variable $X$ and $Z \perp X, Z \sim N(0,1), e^{2 h(X+\sqrt{ } t Z)}$ is concave in $t \geq 0$.

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Costa's EPI in scalar case, [Costa 1985]
For any random variable $X$ and $Z \perp X, Z \sim N(0,1), e^{2 h(X+\sqrt{t} Z)}$ is concave in $t \geq 0$.

## Proof [Villani-2000]:

Computing second derivative of $e^{2 h(X+\sqrt{t} Z)}$ with respect to $t$ yields:

$$
e^{2 h(X+\sqrt{t} Z)}\left[-\left\langle v_{2}^{2}\right\rangle+\left\langle v_{1}^{2}\right\rangle^{2}\right] \leq 0 \stackrel{\left\langle v_{2}+v_{1}^{2}\right\rangle=0}{\Longleftrightarrow}-\left\langle v_{2}^{2}\right\rangle+\left\langle v_{2}\right\rangle^{2} \leq 0
$$

## Main result

Log-convexity of Fisher information in scalar case [Ledoux-Nair-Wang 2020]
Let $X$ be a random variable on some probability space $(\Omega, \mathcal{A}, \mathbb{P})$ with values in $\mathbb{R}$, and $Z \perp X, Z \sim N(0,1)$. Consider $X_{t}:=X+\sqrt{t} Z, t>0$, with probability density function $\mu_{t}^{X}(x)$ with respect to the Lebesgue measure on $\mathbb{R}$. The Fisher information of $X_{t}$ is $\log$-convex in $t$, i.e.

$$
\ln I\left(\mu_{t}^{X}\right)=\ln \int_{\mathbb{R}}\left(\frac{\partial}{\partial t} \ln \mu_{t}^{X}(x)\right)^{2} \mu_{t}^{X}(x) d x
$$

is convex in $t$.

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$$

is convex in $t$.
Proof sketch: Log-convexity of Fisher information is equivalent to

$$
\left(\frac{d}{d t} I\left(\mu_{t}^{X}\right)\right)^{2} \leq I\left(\mu_{t}^{X}\right) \frac{d^{2}}{d t^{2}} I\left(\mu_{t}^{X}\right)
$$

In terms of $\left\langle\prod_{i=1}^{r} v_{k_{i}}^{m_{i}}\right\rangle$, it is equivalent to showing

$$
\left\langle v_{2}^{2}\right\rangle^{2} \leq\left\langle v_{1}^{2}\right\rangle\left\langle v_{3}^{2}+2 v_{1}^{2} v_{2}^{2}+4 v_{1} v_{2} v_{3}\right\rangle
$$

## Proof continued:

In integration by parts formula, choosing $k=2, \varphi=v_{2}$ and $k=2, \varphi=v_{1}^{2}$ will lead to:

$$
\begin{aligned}
& \left\{\begin{array}{l}
\left\langle v_{2}^{2}\right\rangle=-\left\langle v_{1}^{2} v_{2}+v_{1} v_{3}\right\rangle \\
\\
\left\langle v_{1}^{2} v_{2}\right\rangle=-\frac{1}{3}\left\langle v_{1}^{4}\right\rangle
\end{array}\right. \\
& \Rightarrow\left\langle v_{2}^{2}\right\rangle=-\left\langle v_{1} v_{3}+\alpha v_{1}^{2} v_{2}-\frac{1-\alpha}{3} v_{1}^{4}\right\rangle, \forall \alpha \in \mathbb{R} \\
& \Rightarrow\left\langle v_{2}^{2}\right\rangle=-\left\langle v_{1}\left(v_{3}+\alpha v_{1} v_{2}-\frac{1-\alpha}{3} v_{1}^{3}\right)\right\rangle, \forall \alpha \in \mathbb{R}
\end{aligned}
$$

$\xrightarrow{\text { Cauchy-Schwartz }}\left\langle v_{2}^{2}\right\rangle^{2} \leq\left\langle v_{1}^{2}\right\rangle\left\langle\left(v_{3}+\alpha v_{1} v_{2}-\frac{1-\alpha}{3} v_{1}^{3}\right)^{2}\right\rangle, \forall \alpha \in \mathbb{R}$.

## Proof continued:

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$$
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\end{gathered}
$$

To show

$$
\left\langle v_{2}^{2}\right\rangle^{2} \leq\left\langle v_{1}^{2}\right\rangle\left\langle v_{3}^{2}+2 v_{1}^{2} v_{2}^{2}+4 v_{1} v_{2} v_{3}\right\rangle
$$

Suffices to show that

$$
\left\langle\left(v_{3}+\alpha v_{1} v_{2}-\frac{1-\alpha}{3} v_{1}^{3}\right)^{2}\right\rangle \leq\left\langle v_{3}^{2}+2 v_{1}^{2} v_{2}^{2}+4 v_{1} v_{2} v_{3}\right\rangle
$$

holds for some $\alpha \in \mathbb{R}$.
We prove it for $\alpha=2$ by integration by parts formula and some calculation.

Open: Generalization of log-convexity to higher dimensions

- One clear question that is definitely worth addressing is to determine whether the log-convexity of Fisher information along the heat flow also holds for random vectors.
- In particular we ask, whether

$$
\left(\frac{d^{3} h\left(X^{n}+\sqrt{t} Z^{n}\right)}{d t^{3}}\right)\left(\frac{d h\left(X^{n}+\sqrt{t} Z^{n}\right)}{d t}\right) \geq\left(\frac{d^{2} h\left(X^{n}+\sqrt{t} Z^{n}\right)}{d t^{2}}\right)^{2}
$$

where $X^{n}$ and $Z^{n}\left(\sim \mathcal{N}\left(0, I_{n}\right)\right)$ are independent random vectors taking values in $\mathbb{R}^{n}$.

- If $X^{n}$ has independent components, then an application of the Cauchy-Schwartz inequality immediately implies affirmatively the inequality above.


## Summary: Take-aways

In this talk, we studied several non-convex optimization problems:

- Hypercontractive region evaluation for the binary erasure channel
- Distributed source coding
- Modulo sum problem: Obtained improved lower bounds
- Gaussian setting: Alternate proofs of optimality
- Log-convexity of Fisher information: Resolved the log-convexity of Fisher Information conjecture.


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Thank you! Any questions are welcome!

## Supplementary slides to Introduction: Channel coding

$M \in\left[1: 2^{n R}\right] \longrightarrow$ sender: $f^{(n)} \xrightarrow{X^{n}} \xrightarrow{\text { DMC: } W_{Y \mid X}} \xrightarrow{Y^{n}}$ receiver: $g^{(n)} \longrightarrow \hat{M} \in\left[1: 2^{n R}\right]$
Figure 10: Point-to-point communication channel model

## Theorem (Shannon 1948)

The capacity of a $D M C W_{Y \mid X}$ is given by

$$
\begin{equation*}
\mathscr{C}\left(W_{Y \mid X}\right)=\left\{R \geq 0: R \leq \max _{p_{X}} I(X ; Y)\right\} \tag{2}
\end{equation*}
$$

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Figure 10: Point-to-point communication channel model

- $\left\{R \geq 0: R<\max _{p_{X}} I(X ; Y)\right\}$ is an achievable rate region for DMC $W_{Y \mid X}$;
- Optimality: Suffices to show for any DMC $W_{Y \mid X}$ and its product $W_{Y \mid X}^{\otimes 2}$

$$
\max _{p_{X_{1} X_{2}}} I\left(X_{1} X_{2} ; Y_{1} Y_{2}\right)=2 \max _{p_{X}} I(X ; Y)
$$

- It belongs to the non-convex functional family: Let $c>0$,

$$
\max _{p_{X}} I(X ; Y)=\lim _{c \rightarrow \infty} \max _{p_{X Y}} I(X ; Y)-c \sum_{x \in \mathcal{X}} p_{X}(x) D\left(p_{Y \mid X=x} \| W_{Y \mid X=x}\right)
$$

Supplementary slides to Hypercontractivity: $g(x)$ has only one stationary point between $\left(0, \frac{1}{2}\right)$

- Recall $g(x):=\max _{r, s: r \in[0, x], s \in[0,1-x]} f(x, r, s)$.

Hence any stationary point of $g(x)$ will be a stationary point of $f(x, r, s)$.

- Let $y=\frac{2(x-r)}{1-r-s}$; we know from forward hypercontractivity proof the stationary points of $f(x, r, s)$ are in 1-1 correspondence with the roots of

$$
\frac{1-\epsilon}{\epsilon} y^{\lambda_{2}^{\prime}-\lambda_{1}}+y^{1-\lambda_{1}}=\frac{1-\epsilon}{\epsilon}(2-y)^{\lambda_{2}^{\prime}-\lambda_{1}}+(2-y)^{1-\lambda_{1}} .
$$

Hence suffices to show that there is exactly one root of above equation for $y \in(0,1)$.

- This can be shown by taylor expansion and a key observation on the sign change patterns of the coefficients.

Supplementary slides to modulo sum problem: Single-letterize the lower bound on

## Lemma 3.1

Let $\lambda \geq 1$ and let $\left(X^{n}, Y^{n}\right)$ be i.i.d distributed according to $p(x, y)$ where $X, Y$ take values in a finite field. Let $Z^{n}$ be obtained as $Z_{i}=X_{i} \oplus Y_{i}, i=1, . ., n$, i.e. the component-wise modulo sum on the field. Then for any $\lambda \geq 1$ the following holds:

$$
\begin{aligned}
& \min _{\hat{U}: \hat{U} \rightarrow X^{n} \rightarrow Y^{n}} \lambda H\left(Z^{n} \mid \hat{U}\right)-H\left(Y^{n} \mid \hat{U}\right) \\
& \quad=n\left(\min _{U: U \rightarrow X \rightarrow Y} \lambda H(Z \mid U)-H(Y \mid U)\right) .
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## Proof sketch

- Taking i.i.d. copies of the minimizer of the right hand side, left hand side is at most the value of right hand side.

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## Proof sketch

- Taking i.i.d. copies of the minimizer of the right hand side, left hand side is at most the value of right hand side.
- The other direction follows from Markov chain $\left(\hat{U}, Y_{i+1}^{n}, Z^{i-1}\right) \rightarrow X_{i} \rightarrow\left(Y_{i}, Z_{i}\right)$ and Körner-Marton identity.

Supplementary slides to modulo sum problem: Conditions for lower bound to be tight

## Lemma 3.2

The lower bound for the weighted sum-rate $R_{1}+\lambda R_{2}$, for $\lambda \geq 1$ given in Theorem 1 is optimal, i.e. matches the weighted sum-rate of the optimal rate region, if either of the following conditions hold:
(i) $\left.\mathfrak{C}_{\mu(x)}[H(Y)-\lambda H(Z)]\right|_{p(x)}=H(Y)-\lambda H(Z)$ and $Y$ is independent of $Z$,
(ii) $\left.\mathfrak{C}_{\mu(x)}[H(Y)-\lambda H(Z)]\right|_{p(x)}=H(Y \mid X)-\lambda H(Z \mid X)$.

Further if condition $(i)$ holds for some $\lambda_{1}>1$, then it will also hold for $1 \leq \lambda \leq \lambda_{1}$; and if condition (ii) holds for some $\lambda_{2} \geq 1$, then it will also hold for $\lambda \geq \lambda_{2}$.

Supplementary slides to modulo sum problem: Conditions for lower bound to be tight

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## Remark:

A relatively easier condition to verify is the convexity of $H(Y)-\lambda H(Z)$ with respect to the distribution of $X$.

Supplementary slides to Körner-Marton Problem: Application to binary alphabets GF(2)

Notation: We will parameterize the space of distributions over pairs of binary alphabets, $p(x, y)$ as follows:
$P(X=0)=x, P(Y=0 \mid X=0)=c, P(Y=1 \mid X=1)=d$.

Supplementary slides to Körner-Marton Problem: Application to binary alphabets GF(2)

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Proposition 3.1: Optimality of Slepian-Wolf region
The optimal weighted sum-rate of the capacity region is given by the Slepian Wolf region if any of the following conditions hold:
(i) For any $\lambda$, if $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right) \leq 0$, or
(ii) $\lambda \geq\left(\frac{c-\bar{d}}{c-d}\right)^{2}, c \neq d$, and $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right)>0$.
where $\bar{d}=1-d$.

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## Proposition 3.1: Optimality of Slepian-Wolf region

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where $\bar{d}=1-d$.
Remarks:
(i) The condition (i) above is already known and stated as exercise 16.23 page 390 of Csiszár and Körner's book. One can verify that that $H(Z) \geq H(Y)$ is equivalent to $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right) \leq 0$.
(ii) Note that an equivalent proposition can also be stated for the alternate parameterization: $P(Y=0)=y, P(X=0 \mid Y=0)=\hat{c}, P(X=1 \mid Y=1)=\hat{d}$.

Supplementary slides to modulo sum problem: Application to binary alphabets GF(2)

## Proposition 3.2: Optimality of Körner-Marton region

Let $P(X=0)=x, P(Y=0 \mid X=0)=c, P(Y=1 \mid X=1)=d$ where $x=\frac{\sqrt{d \bar{d}}}{\sqrt{d d}+\sqrt{c \bar{c}}}$.
The optimal weighted sum-rate of the capacity region is given by the Körner-Marton region, i.e. using linear codes, if any of the following conditions hold:
(i) For any $\lambda$, if $c=d$, or
(ii) $1 \leq \lambda \leq \lambda_{1}, c \neq d$, and $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right)>0$, where $\lambda_{1}$ is the larger root of the quadratic equation

$$
\lambda^{2}(c-d)^{2}+\lambda\left(2(c-d)(c-\bar{d})-4 d \bar{d}(c-\bar{c})^{2}\right)+(c-\bar{d})^{2}=0
$$

where $\bar{d}=1-d, \bar{c}=1-c$.

Supplementary slides to modulo sum problem: Application to binary alphabets GF(2)

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where $\bar{d}=1-d, \bar{c}=1-c$.
Remarks:
(i) As long as $\left(c-\frac{1}{2}\right)\left(d-\frac{1}{2}\right)>0$ and $x=\frac{\sqrt{d \bar{d}}}{\sqrt{d \bar{d}}+\sqrt{c \bar{c}}}$, the optimal sum-rate will be given by the Körner-Marton region, i.e. using linear codes.
(ii) An equivalent Proposition can also be stated for the alternate parameterization $P(Y=0)=y, P(X=0 \mid Y=0)=\hat{c}, P(X=1 \mid Y=1)=\hat{d}$.

Supplementary slides to modulo sum problem: to higher alphabet fields

## Example 1

For $G F(3)$, one instance of $p(x, y)$ satisfying that $Z$ is independent of $Y$ and $\left.\mathfrak{C}_{\mu(x)}[H(Y)-H(Z)]\right|_{p(x)}=H(Y)-H(Z)$ is given by the following distribution:

$$
p(x, y)=\left[\begin{array}{lll}
0.08 & 0.06 & 0.18 \\
0.08 & 0.18 & 0.06 \\
0.24 & 0.06 & 0.06
\end{array}\right]
$$

Supplementary slides to modulo sum problem: to higher alphabet fields

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0.24 & 0.06 & 0.06
\end{array}\right]
$$

## Example 2

One instance of $p(x, y)$ satisfying $\left.\mathfrak{C}_{\mu(x)}[H(Y)-H(Z)]\right|_{p(x)}=H(Y \mid X)-H(Z \mid X)$ is given by the following distribution:

$$
p(x, y)=\left[\begin{array}{lll}
0.02 & 0.02 & 0.48 \\
0.02 & 0.06 & 0.16 \\
0.06 & 0.02 & 0.16
\end{array}\right]
$$

Supplementary slides to Log-convexity of Fisher Information:
Proof for $\alpha=2$
Expanding what we want to show yields

$$
\left\langle\left(2-\alpha^{2}\right) v_{1}^{2} v_{2}^{2}+(4-2 \alpha) v_{1} v_{2} v_{3}-\frac{1}{9}(1-\alpha)^{2} v_{1}^{6}+\frac{2}{3}(1-\alpha) v_{1}^{3} v_{3}+\frac{2}{3} \alpha(1-\alpha) v_{1}^{4} v_{2}\right\rangle \geq 0
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$$

In integration by parts formula, choosing $k=3, \varphi=v_{1}^{3}$ and that $k=2, \varphi=v_{1}^{4}$ gives

$$
\begin{aligned}
\left\langle v_{1}^{3} v_{3}+v_{2} v_{1}^{4}+3 v_{1}^{2} v_{2}^{2}\right\rangle & =0 \\
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## Supplementary slides to Log-convexity of Fisher Information:

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\left\langle v_{1}^{6}+5 v_{1}^{4} v_{2}\right\rangle & =0
\end{aligned}
$$

Proving above inequality for some $\alpha \in \mathbb{R}$ is equivalent to proving the following inequality

$$
\begin{array}{r}
\left\langle\left(2-\alpha^{2}\right) v_{1}^{2} v_{2}^{2}+(4-2 \alpha) v_{1} v_{2} v_{3}-\frac{1}{9}(1-\alpha)^{2} v_{1}^{6}+\frac{2}{3}(1-\alpha) v_{1}^{3} v_{3}+\frac{2}{3} \alpha(1-\alpha) v_{1}^{4} v_{2}\right\rangle \\
+\beta\left\langle v_{1}^{3} v_{3}+v_{2} v_{1}^{4}+3 v_{1}^{2} v_{2}^{2}\right\rangle+\gamma\left\langle v_{1}^{6}+5 v_{1}^{4} v_{2}\right\rangle \geq 0
\end{array}
$$

for some $\alpha, \beta, \gamma \in \mathbb{R}$.
We successively choose $\alpha=2, \beta=\frac{2}{3}$, and $\gamma=\frac{2}{15}$. Above reduces to $\frac{1}{45}\left\langle v_{1}^{6}\right\rangle \geq 0$.

Supplementary slides to Log-convexity of fisher information Open Problem: Generalization of convexity of the output entropy

- Consider a channel given by

$$
Y^{m}=A X^{n}+Z^{m}
$$

where $A$ is an $m \times n$ (channel-gain) matrix, $X^{n}$ is the input, and $Z^{m}\left(\sim N\left(0, I_{m}\right)\right)$ is the additive Gaussian noise.

- What are the flows in the space of input distributions, say characterized by $X_{t}^{n}$, where $h\left(X_{t}^{n}\right)$ is linear in $t$ and $h\left(Y_{t}^{m}\right)$ is convex in $t$ ?
- An interesting such flow exists in the space of Gaussian vectors [Kubo-Andô 1980]. Let $X_{0}^{n} \sim N\left(0, K_{0}\right)$ and $X_{1}^{n} \sim N\left(0, K_{1}\right)$. Define

$$
K_{t}=K_{0}^{\frac{1}{2}}\left(K_{0}^{-\frac{1}{2}} K_{1} K_{0}^{-\frac{1}{2}}\right)^{t} K_{0}^{\frac{1}{2}}
$$

and $X_{t}^{n} \sim N\left(0, K_{t}\right)$. Then $h\left(X_{t}^{n}\right)$ is linear in $t$ and $h\left(Y_{t}^{m}\right)=\log \left|A K_{t} A^{T}+I\right|$ is convex in $t$.

- Question: Does similar flows exist in a more general setting, i.e. outside the space of Gaussian vectors and more generally for larger class of channels?

